

RS-FSJT-N01 Wind speed transmitter user's Guide (Type 485)

Document version: V2.0







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1. product description

1.1 product description

RS-FSJT-N01 wind speed transmitter, small and light shape, easy to carry and assemble, the three cup design concept can effectively obtain wind speed information, the shell is made of polycarbonate composite material, has good anti-corrosion, anti-erosion and other characteristics, can guarantee The transmitter has been used for a long time without rusting, and it cooperates with the internal smooth bearing system to ensure the accuracy of information collection. It is widely used in the measurement of wind speed in the environment of greenhouse, environmental protection, weather station, ship, wharf, breeding, etc.

1.2Features

- 1. Range: 0-70m/s, resolution 0.1m/s
- 2. Anti-electromagnetic interference treatment
- 3. The bottom outlet method is used to completely prevent the aging problem of the rubber plug of the aviation plug, and it is still waterproof for long-term use.
- 4. Using high-performance imported bearings, low rotation resistance, accurate measurement
- 5. Polycarbonate shell, high mechanical strength, high hardness, corrosion resistance, no rust can be used outdoors for a long time
- 6. The structure and weight of the equipment have been carefully designed and distributed, with small rotational inertia and sensitive response
- 7. Standard ModBus-RTU communication protocol, easy access

1.3 Main Specifications

| DC power supply (default) | 10~30V DC |
|-------------------------------|---------------------------------------|
| Power consumption | ≤0.3W |
| Transmitter circuit operating | -20°C~+60°C, 0%RH~80%RH |
| temperature | |
| | 485 communication (modbus) protocol |
| | Baud rate: 2400, 4800 (default), 9600 |
| Communication Interface | Data bit length: 8 bits |
| | Parity check method: None |
| | Stop bit length: 1 bit |



| | Default ModBus communication address: 1 |
|-----------------------|--|
| | Support function code: 03/04 |
| parameter settings | Use the provided configuration software to configure through the 485 interface |
| Resolution | 0.1m/s |
| Accuracy | ± 0.3 m/s |
| Measuring range | 0~70m/s |
| Dynamic response time | ≤1s |
| Starting wind speed | Default 0.5m/s, high-precision bearings can be selected, upgrade to 0.2m/s |

2. Equipment installation instructions

2.1 Check before installation

Equipment List:

- 1. 1 transmitter device
- 2. 4 mounting screws
- 3. Qualification certificate, warranty card, calibration certificate, etc.
- 4.USB to 485 (optional)
- 5.485 terminal resistance (optional)

2.2 Interface Description

Wide voltage power input can be $10\sim30$ V. When connecting the 485 signal line, please note that the two lines A\B cannot be reversed, and the addresses of multiple devices on the bus must not conflict.

2.3Electrical wiring

| | Thread color | Explanation |
|---------------|--------------|-----------------------|
| power supply | brown | Positive power supply |
| | | (10~30V DC) |
| | black | Negative power supply |
| Communication | green | 485-A |
| | blue | 485-B |

2.4 Field wiring instructions

When multiple 485 model devices are connected to the same bus, there are certain requirements for field wiring. For details, please refer to the "485 Device Field Wiring Manual" in the data



package.

2.5Installation method

Flange installation is adopted, and the threaded flange connection makes the lower pipe fitting of the wind speed sensor firmly fixed on the flange. The chassis is Ø65mm. Four mounting holes of Ø6mm are opened on the circumference of Ø47.1mm. On the bracket, the whole set of instruments is kept at the best level to ensure the accuracy of the wind speed data. The flange connection is easy to use and can withstand greater pressure.



2.6Precautions

- 1. The user should not disassemble it by himself or touch the sensor core to avoid damage to the product.
- 2. Try to stay away from high-power interference equipment, so as not to cause inaccurate measurement, such as frequency converters, motors, etc., when installing and removing the transmitter, you must first disconnect the power supply. Water entering the transmitter can cause irreversible changes.
- 3. To prevent chemical reagents, oil, dust, etc. from directly invading the sensor, do not use it for a long time in the environment of condensation and extreme temperature, and strictly prevent cold and hot shocks.

3. Configuration software installation and use

3.1 Software selection

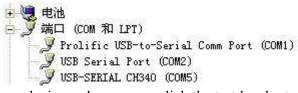
Open the data package, select "Debug software" --- "485 parameter configuration software",





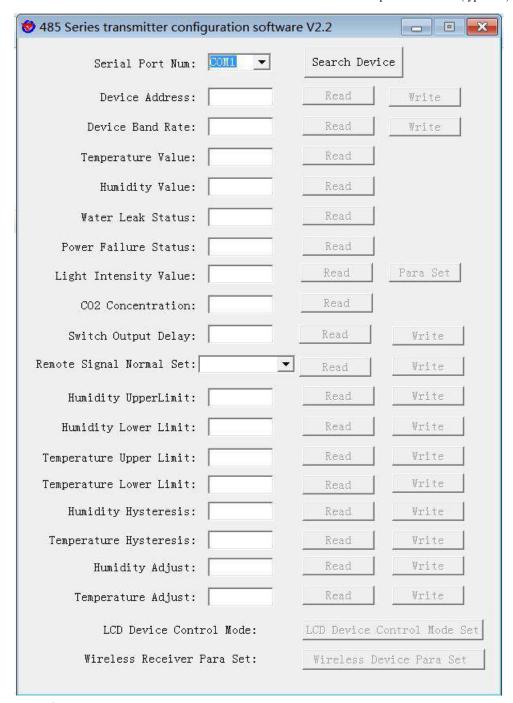
3.2 parameter settings

①, select the correct COM port ("COM" port in "My Computer-Properties-Device Manager-Port" to view the COM port), the following figure lists the driver names of several different 485 converters.



- ②, only connect one device and power on, click the test baud rate of the software, the software will test the baud rate and address of the current device, the default baud rate is 4800bit/s, the default address is 0x01.
- 3 Modify the address and baud rate according to the needs of use, and at the same time, you can query the current functional status of the device.
- ④ If the test is unsuccessful, please recheck the device wiring and 485 driver installation.





4. letter of agreement

4.1 Communication basic parameters

| Coding | 8-bit binary |
|----------------|---|
| Data bit | 8 bit |
| Parity bit | no |
| Stop bit | 1 person |
| Error checking | CRC (Redundant Cyclic Code) |
| Baud rate | 2400bit/s, 4800bit/s, 9600 bit/s can be set, the factory default is 4800bit/s |

4.2 Data frame format definition



Using Modbus-RTU communication protocol, the format is as follows:

Time for initial structure \geq 4 bytes

Address code = 1 byte

Function code = 1 byte

Data area = N bytes

Error check = 16-bit CRC code

End structure ≥ 4 bytes of time

Address code: the address of the transmitter, which is unique in the communication network (factory default 0x01).

Function code: the instruction function instruction issued by the host, this transmitter only uses the function code 0x03 (read register data).

Data area: The data area is specific communication data, pay attention to the high byte of 16bits data first!

CRC code: two-byte check code.

Host inquiry frame structure:

| address co | function co | Register start ad | Register lengt | Check digit 1 | Check digit hig |
|------------|-------------|-------------------|----------------|---------------|-----------------|
| de | de | dress | h | ow | h |
| 1byte | 1byte | 2byte | 2byte | 1 byte | 1byte |

Slave response frame structure:

| | | Effective byt | Data area | | Nth data area | Check code |
|-------|-------|---------------|-----------|-------|---------------|------------|
| ode | code | es | | area | | |
| 1byte | 1byte | 1byte | 2byte | 2byte | 2byte | 2byte |

4.3 Register address

| Register address | PLC or configuration | content | operating |
|------------------|----------------------|-------------------------------|-----------|
| | address | | |
| 0000 H | 40001 | Instantaneous wind speed | Read only |
| | | The uploaded data is 10 times | |
| | | the real value | |

4.4 Communication protocol example and explanation

Example: Read the wind speed value of device address 0x01

Inquiry frame:

| 1 2 | | | | | |
|--------------|---------------|----------------|-------------|----------------|----------------|
| address code | function code | starting addre | Data length | Check digit lo | Check digit hi |
| | Tunetion code | SS | Data length | w | gh |



| 0x01 0x03 0 | 0x00 0x00 0x00 0x01 | 0x84 | 0x0A |
|-------------|---------------------|------|------|
|-------------|---------------------|------|------|

Response frame: (for example, the current wind speed is 8.6m/s)

| address co | function cod | Returns the numb | Current wind | Check digit lo | Check digit h |
|------------|--------------|-------------------|--------------|----------------|---------------|
| de | e | er of valid bytes | speed value | w | igh |
| 0x01 | 0x03 | 0x02 | 0x00 0x56 | 0x38 | 0x7A |

Wind speed calculation:

Current wind speed: 0056H (hexadecimal) = 86=> Wind speed = 8.6m/s

5. Common problems and solutions

5.1 Device cannot be connected to PLC or computer

possible reason:

- 1) The computer has multiple COM ports, and the selected port is incorrect.
- 2) The device address is wrong, or there are devices with duplicate addresses (the factory default is all 1).
- 3) Baud rate, check mode, data bit, stop bit error.
- 4) The host's polling interval and waiting time for answering are too short, and both need to be set above 200ms.
- 5) The 485 bus is disconnected, or the A and B lines are reversed.
- 6) If the number of devices is too large or the wiring is too long, power should be supplied nearby, and a 485 booster should be added, and a 120Ω terminal resistance should be added.
- 7) The USB to 485 driver is not installed or damaged.
- 8) The equipment is damaged.

6. contact details

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Province

Post code: 250101 Phone: 400-085-5807 Website: www.renkeer.com

Cloud platform address: en.0531yun.cn Or: eniot.0531yun.cn

Web QR:



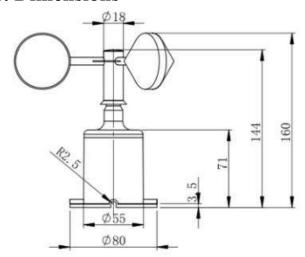


7. Document history

V1.0 document creation.

V2.0 documentation update.

8. Dimensions



Overall height: 160

Spindle height: 144

Base height: 71

Base diameter: ϕ 80

unit (mm)

