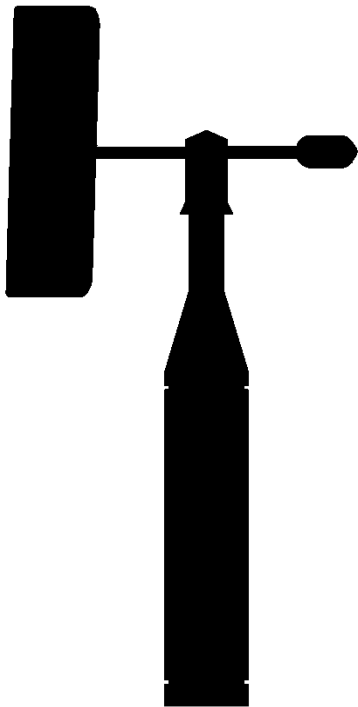


Wind Data Logger

MODEL: SB-WD

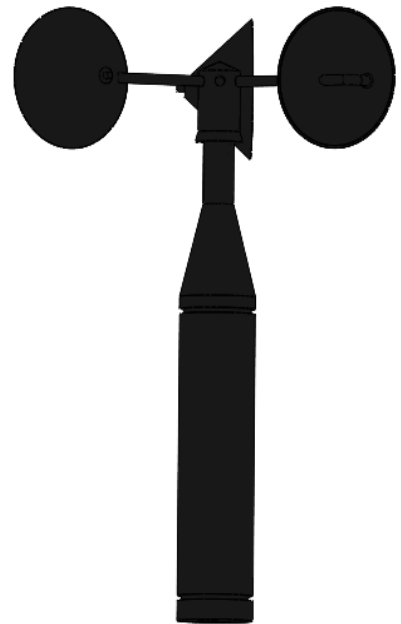
SMART BIENE.



SB-DS
Wind Direction Sensor



SD-WD
Wind Data Logger



SB-SS
Wind Speed Sensor

Smart Biene
Email: info@smartbiene.com



Description

SB-WD wind speed and direction Data Logger is a reliable device in weather stations:

- **SB-WD** measures data from 3 different sensors (wind speed or direction) with a high resolution and reliable design and logging data on **Micro SD Card**.
- Also you can see online graph of measured values by **Device Software** on a PC with **USB port**.
- You can have analogue and digital outputs to command other devices or alarms.



Figure 1: SB-WD

MEASURING SPECIFICATIONS

Reference Condition: 25 °C (77 °F):

- Accuracy: $\pm 0.15\%$ FS (URL).
- Stability: $\pm 0.25\%$ FS/year.
- Response Time: 30msec.
- Output Resolution: 0.05% FS (URL)
- LCD Accuracy: $\pm 0.05\%$ FS (URL) + last digit

*URL: Accuracy includes the effects of linearity, Hysteresis, and repeatability.

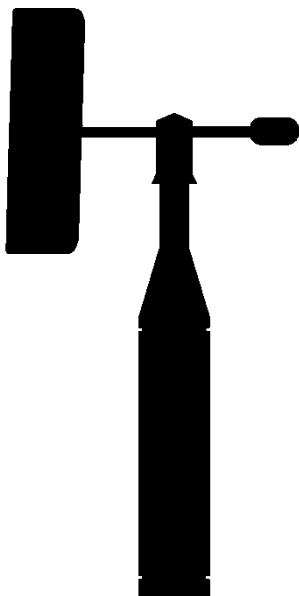


Figure 2: Wind Direction Sensor

ELECTRICAL SPECIFICATIONS

- Display: 2.8 inch full-color TFT LCD with LED backlight.
- Power Supply: 24VDC.
- Current Output: 0-10 , 0-20 , 4-20 mA , MAX Load: 500Ω
- Relay Output: 2 or 4 Relays, 0.5A - 220VAC or 4A-30VDC.
- 2 Wire Modbus-RTU communication protocol.
- All In/Out Ports: 30VDC Circuit Protected.

ENVIRONMENTAL CONDITIONS

- Operating temperature:
 - **SB-WD**: -10 to +70°C
 - **SB-SS**: -25 to +70°C
 - **SB-DS**: -25 to +70°C
- Humidity: max. 90%
- Relative vibration: 2g (10...2000 Hz)
- Shock: 5g/ 8 ms.
- Robust NEMA 4X (IP66) aluminum die-cast housing for SB-WD.
- Anodized Aluminum (IP66) body for wind speed and direction sensors **SB-SS & SB-DS**.

**CAUTION**

- Some liquid mixtures are dangerous. This includes mixtures that occur because of contamination. Make sure that the device is safe to use with the necessary media.
- It is dangerous to ignore the specified limits for the device or to use the device when it is not in its normal condition. Use the applicable protection and obey all safety precautions.
- **Keep LCD away from direct sunlight.**
- Before you start an operation or procedure, make sure that you have the necessary skills (if necessary, with qualifications from an approved training establishment).
- Follow good engineering practice at all times.

**ESD CAUTION**

ESD (electrostatic discharge) sensitive device: Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



TERMINAL WIRING

01. Current Output (+)
02. Current Output (-)
03. **Sensor connection (+24VDC)**
04. **Sensor connection (GND)**
05. RS-485 (Modbus-RTU): A - output
06. RS-485 (Modbus-RTU): B - output
07. **Sensor 3 connection (RS-485 input-B)**
08. **Sensor 3 connection (RS-485 input-A)**
09. **Sensor 2 connection (With 4-20mA input)**
10. **Sensor 1 connection (With 4-20mA input)**
11. Relay-1: COM
12. Relay-1: NC
13. Relay-1: NO
14. Relay-2: COM
15. Relay-2: NC
16. Relay-2: NO
17. Relay-3: COM
18. Relay-3: NC
19. Relay-3: NO
20. Relay-4: COM
21. Relay-4: NC
22. Relay-4: NO

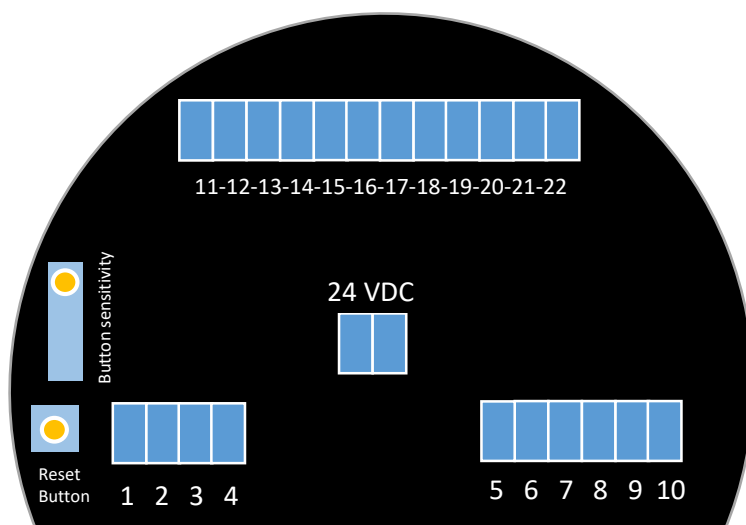


Figure 3: Panel Terminal Wiring

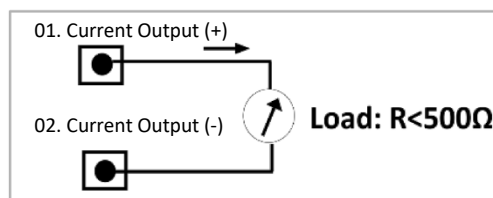
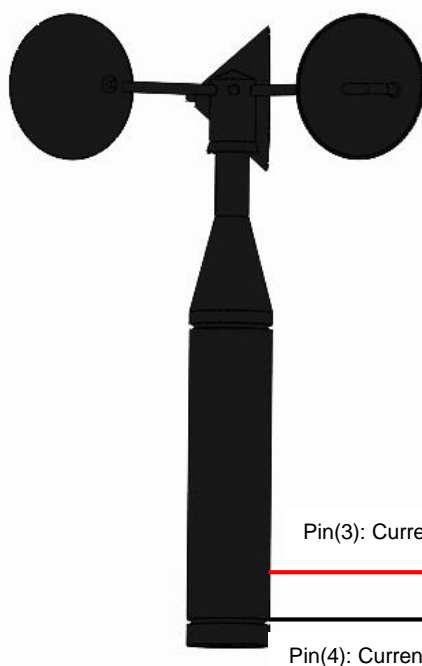


Figure 4: Current Output Wiring

Wind Speed and direction sensor connection to SB-WD

You can connect up to 3 wind sensors (speed or direction) to SB-WD. Sensor output types should be:

- 1- Direction or speed sensor with current output (4-20mA). (Connecting to terminal 10&4) **sensor 1**.
- 2- Direction or speed sensor with current output (4-20mA). (Connecting to terminal 9&4) **sensor 2**.
- 3- Direction or speed sensor with Modbus output. (connecting to terminal 7&8) **sensor 3**.



Pin(3): Current Output (-)

Pin(4): Current Output (+)

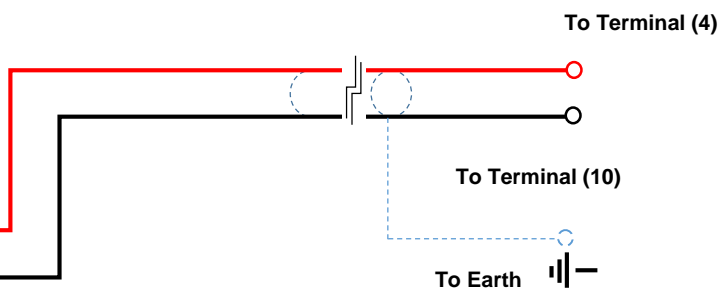


Figure 5: 2-wire Wind Speed Sensor with 4-20mA output wiring to SB-WD as sensor 1.



Connection Cable

The instrument is connected with standard two-wire cable without screen. If electromagnetic interference is expected which is above the test values of EN 61326-1 for industrial areas, **screened cable should be used**.

If screened cable is required, we recommend connecting the cable screen on both ends to ground potential. In the sensor, the screen should be connected directly to the internal ground terminal. The ground terminal on the outside of the housing must be connected to the ground potential (with low impedance).

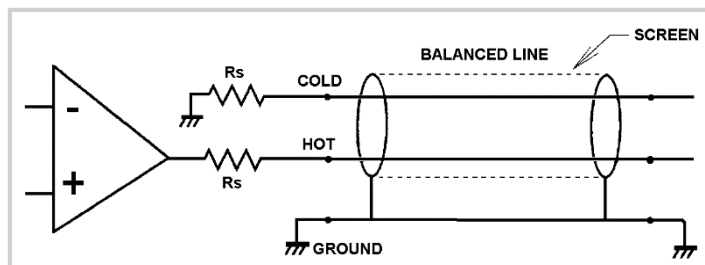


Figure 6: screened cable wiring

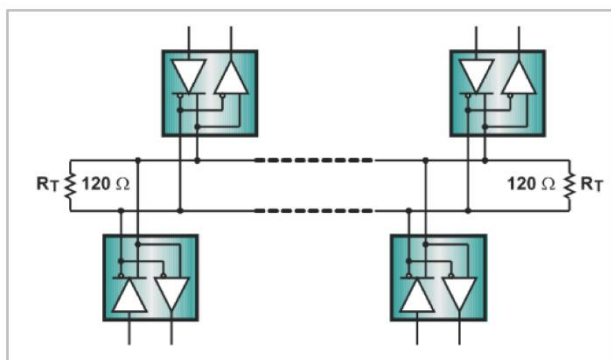


Figure 7: RS-485 network topology

RS-485 Network Topology.

RS-485 suggests its nodes to be networked in a daisy-chain, or bus topology.

In this topology, the participating drivers, receivers, and transceivers connect to a main cable trunk via short network stubs. The interface bus can be designed for half-duplex transmission.

$$R_i = 120\Omega$$

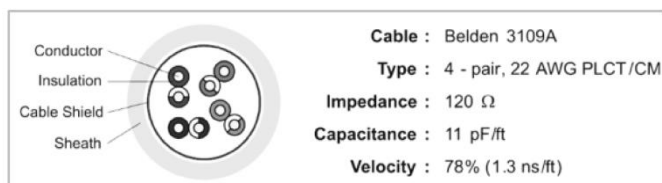


Figure 8: RS-485 Cable



MODEL SELECTION – WIND DATA LOGGER



Device Type: _____

WD: Wind Data Logger.

Output: _____

1: Current Output (0-20/4-20 mA)

0: NO Current Output

1: Modbus-RTU Output

0: NO Modbus-RTU Output

2: Two-Relay Output

4: Four-Relay Output

Options: _____

UL: USB Connection & Data Logger.

T: External Trimming Potentiometer.

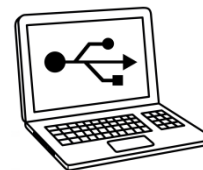
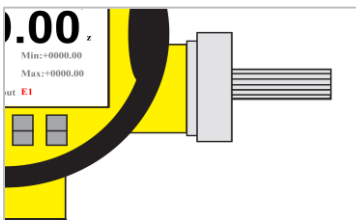
Adjustment via PC-USB

- You can also adjust device via USB connecting to pc and using device Software, refer to page 17 .

EXTERNAL TRIMPOT

External trimming Potentiometer can be used for External Configuration of ALARM Value:

- No need to Enter in Menu
- You can see alarm value in main page 1.
- User friendly for machine operators.





MODEL SELECTION – WIND SPEED SENSOR

S B - S S - 1 - 1

Device Type:

SS: Wind speed sensor.

Measuring Range:

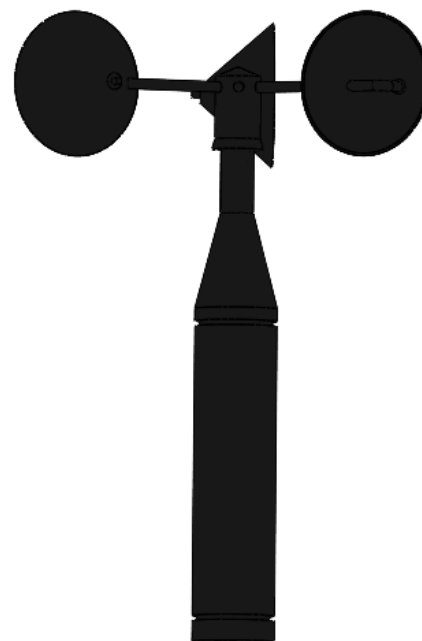
1: 0 to 50 m/s With 0.1m/s Accuracy

2: 0 to 75 m/s With 0.1m/s Accuracy

3: 0 to 100 m/s With 0.1m/s Accuracy

Output:

1: 4-20 mA & RS-485



TERMINAL WIRING – WIND SPEED SENSOR

1. RS485-A
2. RS485-B
3. Current Output (-) (Active)
4. Current Output (+) (Active)
5. GND – Supply
6. 24VDC – Supply
7. Earth





MODEL SELECTION – WIND DIRECTION SENSOR

S **B** - **D** **S** - **1** - **1**

Device Type: _____

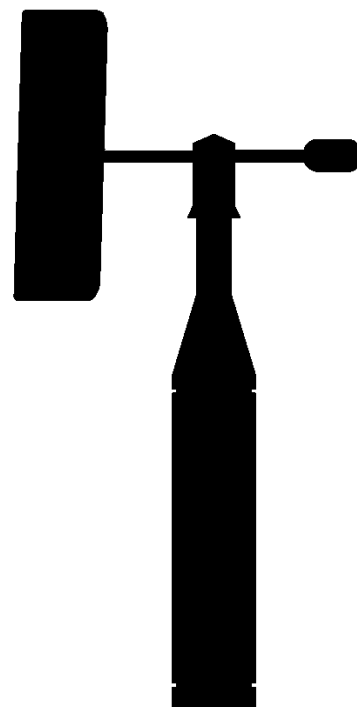
DS: Wind direction sensor.

Measuring Range: _____

1: 0 to 360 deg With 0.1 deg Accuracy

Output: _____

1: 4-20 mA & RS-485



TERMINAL WIRING – WIND DIRECTION SENSOR

- RS485-A
- RS485-B
- Current Output (-) (Active)
- Current Output (+) (Active)
- GND – Supply
- 24VDC – Supply
- Earth





OPERATION

Touch Buttons:

Three infrared touch buttons are designed for device configuration. Under extremely rare case, the infra-red switches may respond unexpectedly in such conditions as sticking ball of water or extraneous substances on the surface of display panel glass according to the principle of infra-red switch operation. It is probability rises in such cases as sticking rain water by storm or other similar situation and washing up work near panel installation place. Either to illuminate or stop illuminating the infra-red switches by the flashlight may cause the miss-reaction. During data entry the device remains on-line, the Outputs continue to indicate the actual operating values. The individual key functions are described below:

Up Button: (▲)

This key is one of the two arrow keys. It's
Used for increasing digits, going up in
Menu subpages, changing main pages, etc.

Menu / Enter Button: (▶)

It's used for entering in menu (hold it
3sec), Entering in submenus, Selecting digits, etc.

Back Button: (◀)

It's used for turning off the LCD back-
Light (hold it 3sec), return to main
Pages from menu, return from submenus
In menu, etc.

RESET FACTORY

- If it is necessary to restore all settings to the original factory configuration, touch and hold menu and back buttons (▶◀ 3SEC) until the display asks for reset factory and then select YES.

Notice: In reset factory mode all settings return to its default factory configuration and when you reset panel by power **off & on**, or by reset push-button in back end of panel all settings will not change.

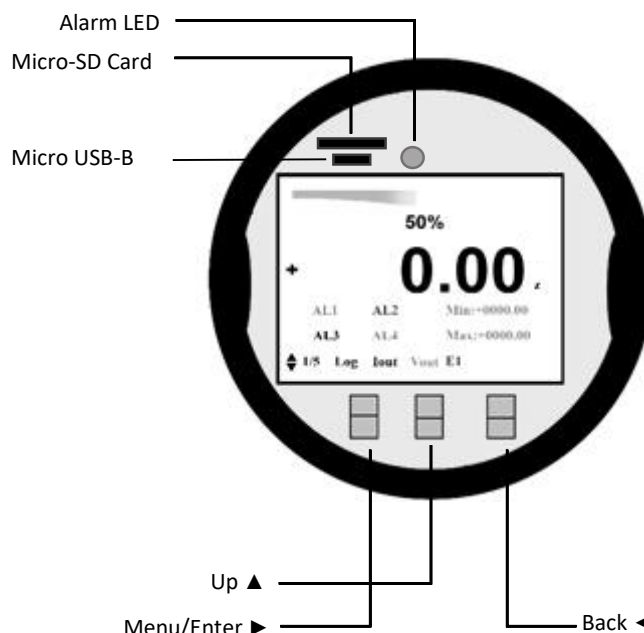


Figure 9: Panel front View

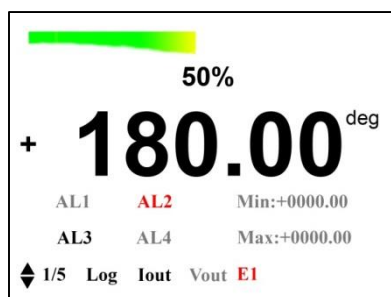
NOTICE

- To improve sensitivity of touch buttons set the screw in terminal panel, which is mentioned on page 3. In electrical diagram section. **Reset device and use touch buttons setting.**
- Don't open the device front panel cover (keep clean inside surface of glass - that's **vital**)
- Operate the display unit under the condition where direct sunlight, etc... do not shine to the setting switches directly when the parameter setting operation is carried out.
- Use switches with panel glass cover.**
- If dirt, dust or other substances surfaces on the display panel glass, wipe them clean with a soft dry cloth.
- The operation with dirty gloves may cause a switch response error.
- If dirt, dust or other substances surfaces on the display panel glass, wipe them clean with a soft dry cloth.



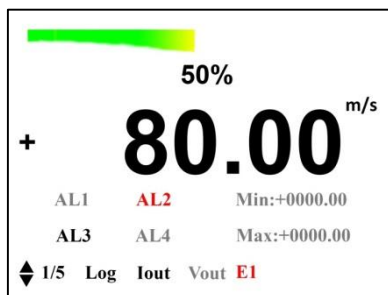
MAIN PAGES

- 5 Main Pages are Designed for measuring parameters, output status, you can move between main pages by up button(▲):
 - MAIN PAGES 1/5 to 3/5: measuring values and parameters, output status ...
 - ERRORS PAGE 4/5: Describes errors which are shown in MAIN PAGES.
 - INFO PAGE 5/58: Describes some features and specifications of device such as serial number, model code, measuring range...



MAIN PAGES (1/5 to 5/5)

- Measured Values: the main digits show measured values and parameters such as wind speed & wind direction.
- Alarms status: Bold when enabled, and red when excited.
- MIN & MAX values: Bold when enabled.
- Current Output (Iout) status: Bold when Enabled.
- Data Logger (Log) status: Bold when Enabled.
- Percent of Measuring Range (refer to info page) Graph: 50% as shown in figures.
- Errors status: E1 ... (Refer to error page.)
- Measuring Unit: m/s ... as show in figures.





ERROR PAGE (4/5)

- E1: this error appears when data logging is impossible such as the absence of SD-Card, full memory, or any other Hardware based problems.
- E2: this error appears when sensor connection to device has problem such as disconnecting, short circuit or any damage to sensor cables.
- E3: this error appears when measured value exceeds the measuring range of sensor. This error can result in damage of device.
- E4: this error appears when measuring value is out of measuring outputs. For example if 20 mA configured equal to 50 m/s and measured value is more than 50 m/s, this error appears.

Errors:

E1: Logging Data Problem

E2: Sensor Connection Problem

E3: Out of Analogue Output Range

E4: Out Of Measuring Range of Sensor

◆ 7/8 Log Iout Vout **E1**

Info:

Tag id:xxxxxxxxxxxxxxxxxxxxxx

Serial Number:-----

Model:-----

Production Date:yyyy/mm

Sensor Range:xxx

Web Site:www.SmartBiene.com

◆ 8/8 Log Iout Vout **E1**

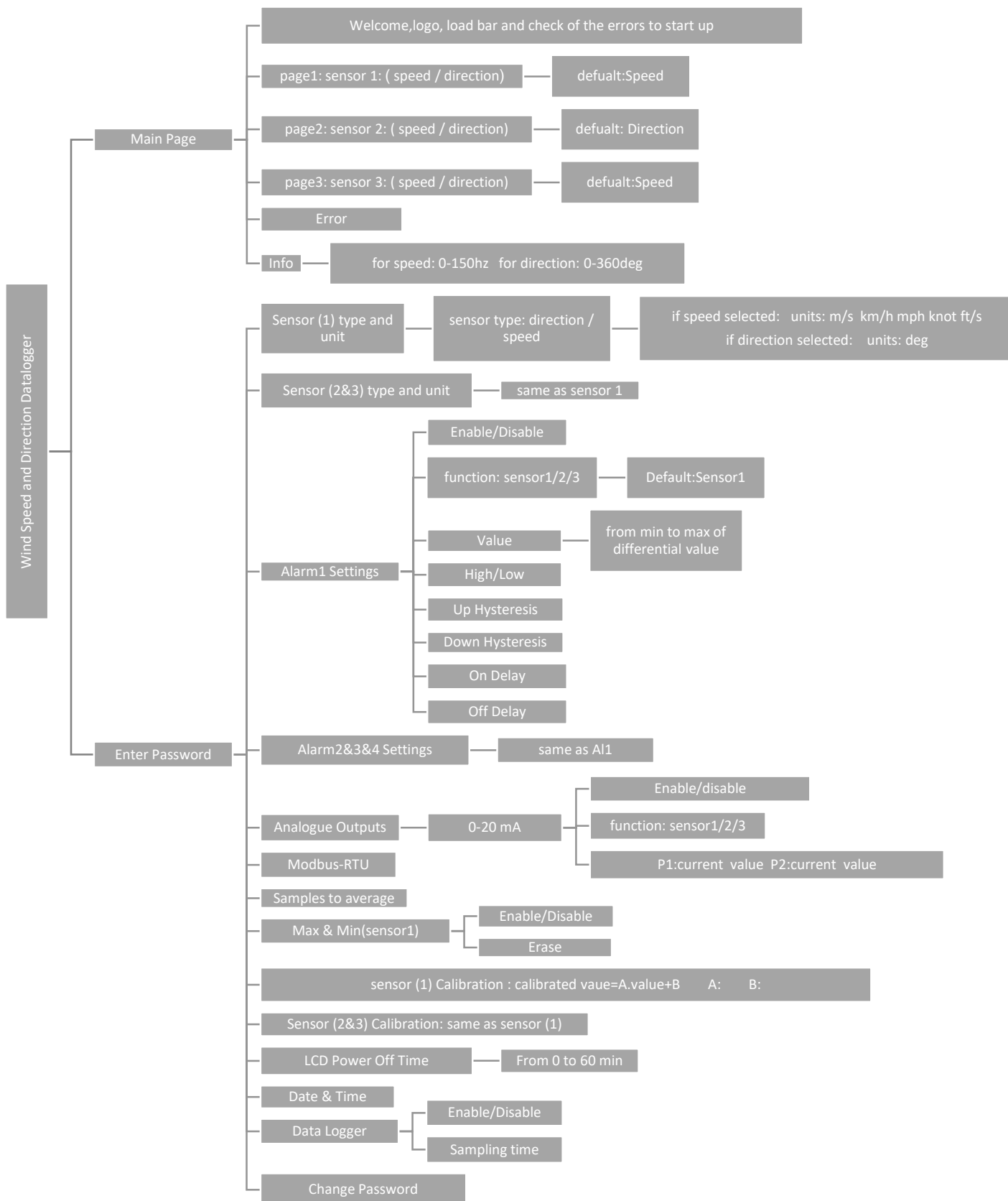


INFO PAGE (5/5)

- Tag ID: you can change Tag ID **only** by PC Software of device and modbus protocol.
- Serial Number, Model code, sensor range and production date are Factory registered information.
- **NOTICE:** percentage value in main page 1 is based on sensor range. Min-Max of range is equal to 0-100% of measured value.



MENU QUICK GUIDE





RESET FACTORY - RESET PASSWORD

- If it is necessary to restore all menu settings to the original factory configuration, touch and hold menu and back buttons (►◄ 3SEC) until the display ask for reset factory and then select YES.
- **If you have forgotten Password, so you can use Reset factory configuration, it changes password to 000.**

Menu:

Please Enter Password

0 0 0

Press&hold menu after entering password

HOW TO ENTER MENU

- Touch and hold menu button for 3sec and enter password. (► 3SEC)
- Use menu button to move between digits. (►)
- Use up button to increase and decrease digits. (▲)
- Touch and hold menu button for 3sec to enter menu (if password is correct). (► 3SEC)
- If you have forgotten password , touch and hold menu and back buttons to (►◄ 3SEC)

Menu:

Sensor 1 Type And Unit

[ST] S2 S3 A1 A2 A3 AO MD SA
MM OC1 OC2 OC3 LCD DT DL CP ▼

UNIT SELECTION

After enter in menu, first setting is measuring unit:

- Touch menu to enter units (►)
- Use up button to select between sensor 1 , 2 and 3. (▲)
- Touch menu again to select sensor type of each sensor input of panel you can select direction or speed for each sensor . (►)
- Then touch menu again to select unit for selected sensor type.
 - You can select units of **m/s km/h mph knot ft/s** for speed sensor and **deg** for direction sensor.
- Touch back button to exit from unit setting. (◄)

Menu:Sensor 1 Type&Unit:

Sensor type:

Direction Speed

[ST] S2 S3 A1 A2 A3 AO MD SA
MM OC1 OC2 OC3 LCD DT DL CP ▼



ALARM SETTINGS

Based on relay selection you can configure two or four relays setting in menu:

Alarm x setting:

- Touch up to select Alarm x settings. (▲)
- Touch menu. (►)
- **Enable or disable:** you can disable or enable alarm (relay). Use up to move and finally use menu button to select disable or enable. (▲►)
- **Function:** Select from sensor 1, 2 or 3 which values should be used for Alarm!
- **Value:** Touch up button and then menu to change alarm value, use menu to move between digits and up change values. (▲►)
- **High or low:** Touch up button and then menu button to select High or Low setting for alarm:
 - **High:** when measured value exceeds alarm value, then relay excites.
 - **Low:** when measured value lessens than alarm value, then relay excites.
- **Hysteresis:** you can define up hysteresis values for alarm value: Touch up button and then menu button to change hysteresis values, use menu to move between digits and up to change values. (▲►)
 - **Up hysteresis:** when alarm is in low mode, and relay is excited; when measured value exceeds alarm value + up hysteresis, relay returns to its normal status.
 - **Down hysteresis:** when alarm is in high mode, and relay is excited; when measured value lessens alarm value - down hysteresis, relay returns to its normally situation.
- **Delay:** you can define on and off delay for alarms; you can define up and down hysteresis values for alarm value: Touch up button and then menu to change hysteresis values, use menu to move between digits and up to change values. (▲►)
 - **Delay on:** delay for relay excitation.
 - **Delay off:** delay for relay to return to its normal status.
- Touch back button to return to the main menu

Menu:

Alarm1 Settings

UN **AL1** AL2 AL3 AL4 AO RS
STA MM ZO OC LCD DT DL CP ▼

Menu: A1 Settings:

ED
VL
HL
UH
DH
OD
FD

Disable

UN **AL1** AL2 AL3 AL4 AO RS
STA MM ZO OC LCD DT DL CP ▼

Menu: A1 settings:

FU
ED
VL
HL
UH
DH
OD
FD

Function:
Sensor1 Sensor2
Sensor3

S1 S2 S3 **AL1** A2 A3 AO MD SA
MM OC1 OC2 OC3 LCD DT DL CP ▼

Menu: A1 Settings:

ED
VL
HL
UH
DH
OD
FD

Value:
+ 0 0 0 0 . 0 0

UN **AL1** AL2 AL3 AL4 AO RS
STA MM ZO OC LCD DT DL CP ▼

Menu: A1 Settings:

ED
VL
HL
UH
DH
OD
FD

Low

UN **AL1** AL2 AL3 AL4 AO RS
STA MM ZO OC LCD DT DL CP ▼

Menu: A1 Settings:

ED
VL
HL
UH
DH
OD
FD

Down Hysteresis:
+ 0 0 0 0 . 0 0

UN **AL1** AL2 AL3 AL4 AO RS
STA MM ZO OC LCD DT DL CP ▼

Menu: A1 Settings:

ED
VL
HL
UH
DH
OD
FD

On Delay:
0 0 : 0 0

UN **AL1** AL2 AL3 AL4 AO RS
STA MM ZO OC LCD DT DL CP ▼



ANALOGUE OUTPUT

Based on model order there is one analogue output for device:

- Touch up and menu to enter in an analogue output setting: (▲►)
- Touch up and menu to select 0-20mA settings: (▲►)
- **0-20mA:**
 - You can disable or enable 0-20mA output. Use up to move and finally use menu button to select disable or enable. (▲►)
 - **Function:** Select from sensor 1, 2 or 3 which values should be used for Alarm!
 - **point Value & point mA:**

For this output type you can define a linear relation between measured value (between measuring range) and current output (between 0 to 20mA) by means of two points. Thus we have:

Point 1 value ↔ point1 mA

Point 2 value ↔ point2 mA

Thus you can have 4-20mA or 0-20mA ... current outputs for your measurement range!

Touch up button and then menu to change alarm value, use menu to move between digits and up to change values. (▲►)

Menu:Analogue Outputs:mA

mA

V

ED

P1

P1A

P2

P2A

Point1 mA:

00.00 mA

UN AL1 AL2 AL3 AL4

AO

RS

STA MM ZO OC LCD DT DL CP

◆

Menu:

Analogue Outputs

UN AL1 AL2 AL3 AL4

AO

RS

STA MM ZO OC LCD DT DL CP

◆

Menu:Analogue Outputs:V

Function:

Sensor1 Sensor2
Sensor3

FU

ED

P1

P1A

P2

P2A

S1 S2 S3 A1 A2 A3

AO

MD SA

MM OC1 OC2 OC3 LCD DT DL CP

◆

Menu:Analogue Outputs:

mA

V

0-20mA

UN AL1 AL2 AL3 AL4

AO

RS

STA MM ZO OC LCD DT DL CP

◆

Menu:Analogue Outputs:mA

Point1 Value:

+ 0000.00

ED

P1

P1A

P2

P2A

UN AL1 AL2 AL3 AL4

AO

RS

STA MM ZO OC LCD DT DL CP

◆



RS-485 (Modbus-RTU)

Based on model order Modbus-RTU communication protocol is possible for device, Touch up button and then menu to change address value. (▲►)

- Refer to **Modbus-RTU Register Map manual** for transmitter.
- In menu you can define device as a slave with address 001 to 247.

MAX & MIN

- you can record and display max and min of measured value on **sensor1 only** in main page 1:
 - Enable or disable:** in Min & Max menu, Use up to move and finally use menu button to select disable or enable. (▲►)
 - Erase:** in Min & MAX menu, Use up to move and finally use menu button to select Erase and then select yes to erase and reset Max & Min values displayed in main page 1. (▲►)

TWO POINT CALIBRATION

You can use this setting for field calibration of **sensor 1, 2 & 3** which is selected:

- you can measure any direction or speed and Define a Linear equation between measured signal and display or output values. Definition of linear equation is possible by two-point calibration of signal:
 - apply first reference by sensor(for example apply 20m/s reference wind speed) as point 1
 - enter corresponding value for point1
 - Then press menu to calibrate and receive "point1 calibrated" command.
 - Do this for second point
 - Thus you have linear relation between displayed (or output value) and input signal As show in fig 10.

Menu:

Modbus Address:

001

UN AL1 AL2 AL3 AL4 AO TS MD
STA MM OC LCD ME DT DL CP

Menu:

Max & Min

UN AL1 AL2 AL3 AL4 AO RS
STA MM ZO OC LCD DT DL CP

Menu:Sensor1 Calibration

Disable **Enable**

S1 S2 S3 A1 A2 A3 AO MD SA
MM OC1 OC2 OC3 LCD DT DL CP

Menu:Sensor1 Calibration

Value P1:

+ 0 0 0 0 . 3 3 m/s

S1 S2 S3 A1 A2 A3 AO MD SA
MM OC1 OC2 OC3 LCD DT DL CP

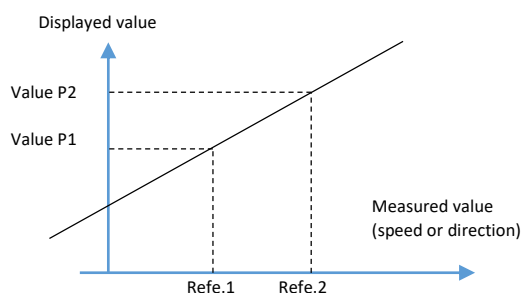


Figure 10: point calibration



LCD POWER OFF TIME

You can define a power off time for LCD Backlight:

- Values form 1 to 60 minutes.
- Also you can select disable for continuously LCD Backlight ON. **Not Recommended!**

Menu:

LCD Power Off Time:

05 min

UN AL1 AL2 AL3 AL4 AO RS
STA MM ZO OC **LCD** DT DL CP

DATE & TIME

For Data Logger option, you can set date and time, use menu to move between digits and up to change values. (▲►)

- Use CR2032- 3V battery on electrical board behind LCD.
- For normal operation, life of battery is 2 years.
- If don't use battery, date and time will reset by device power off.

Menu:

Date & Time:

2012/12/27

14:48

UN AL1 AL2 AL3 AL4 AO RS
STA MM ZO OC LCD **DT** DL CP

DATA LOGGER

With this option you can measure and record data of **sensor 1, 2 & 3** to SD-Card:

- Recording Data on 2GB MICRO SD-Card with date and time tag. Saving data as a TEXT file.
- **Sampling period:** change sampling period from 1sec to 9999 sec. use menu to move between digits and up to change values. (▲►)

Menu:DataLogger:

ED
ST

0 0 0 1 Sec

UN AL1 AL2 AL3 AL4 AO RS
STA MM ZO OC LCD DT **DL** CP

CHANGE PASSWORD

You can change Password for entering menu:

- Enter menu: change password
- Enter old password
- Enter new password
- Confirm new password, enter new password again.
- Password changed!

If you have forgotten password, use reset factory option.

Menu:ChangePassword:

Please Enter New Password

0 0 0

Menu:ChangePassword:

Please Confirm New Password

0 0 0



Modbus-RTU Register Map

Format of the master message

each message sent by the master obeys the following format:

Device Address	Function code	n byte parameters (optional)	CRC16_L	CRC16_H
----------------	---------------	---------------------------------	---------	---------

Device Address: Address of the device.

Address 0 is reserved for broadcasting.

Addresses 1 to 247 can be used for this device

Function code: Function number

this function code use for read or write data.

Parameters: parameters different based on function

CRC16: 16-bit checksum to verify that data received correctly

Format of the slave message

a message transmitted by the slave obey the following format:

Device Address	Function code	n byte parameters (optional)	CRC16_L	CRC16_H
----------------	---------------	---------------------------------	---------	---------

- Device Address: **Address of the device.**
- Function code: **The function number is same to the function number sent by the master.**
- Data: **Any data requested via the function follow here. If error occurred function code Oared with 0x80 and returned CRC16**

Exception errors

If message has been received correctly (no transmission error has occurred), but the transmitted function number and/or the parameters are invalid. **The slave responds an exception error**, unless the message has been received in broadcasting mode. The message transmitted as a response by the slave has the following format:

Device Address	Function code	Exception code	CRC16_L	CRC16_H
----------------	---------------	----------------	---------	---------

Modbus RTU Frame Layout

> 3.5 char Delay time	8 bit address	8 bit Function code	n*(8 bit data)	CRC16	> 3.5 char Delay time
--------------------------	---------------	------------------------	----------------	-------	--------------------------

The entire message frame must be transmitted continuously. If an interval of more than 1.5 character times occurs between two characters, the message frame is declared incomplete and discarded by the receiver.

Description of MODBUS functions

F3: Read registers on MODBUS address space

F6: Write single register on MODBUS address space

F8: MODBUS Echo function

F16: Write multiple registers on MODBUS address space

Function 3: MODBUS Read Register

Read single or multiple registers in the MODBUS address space starting with Start Address. Note that the data returned based on “MODBUS Register Map”.

**Request:**

Device Address	0x03	Start addr H	Start addr L	#Reg H	#Reg L	CRC16_L	CRC16_H
----------------	------	--------------	--------------	--------	--------	---------	---------

Response:

Device Address	0x03	# Bytes	Data H	Data L	...	CRC16_L	CRC16_H
----------------	------	---------	--------	--------	-----	---------	---------

Error:

Device Address	0x83	Error	CRC16_L	CRC16_H
----------------	------	-------	---------	---------

Function 6: MODBUS Write Single Register

This function is similar to F16, but writes only 1 register. Note, that the data will be written based on “MODBUS Register Map”.

Request:

Device Address	0x06	Start addr H	Start addr L	Data H	Data L	CRC16_L	CRC16_H
----------------	------	--------------	--------------	--------	--------	---------	---------

Response:

Device Address	0x06	Start addr H	Start addr L	Data H	Data L	CRC16_L	CRC16_H
----------------	------	--------------	--------------	--------	--------	---------	---------

Error:

Device Address	0x86	Error	CRC16_L	CRC16_H
----------------	------	-------	---------	---------

Function 8: MODBUS Echo Test

This function used to perform a quick line check. It returns the data that received.

Request:

Device Address	0x08	0	0	Data H	Data L	CRC16_L	CRC16_H
----------------	------	---	---	--------	--------	---------	---------

Response:

Device Address	0x08	0	0	Data H	Data L	CRC16_L	CRC16_H
----------------	------	---	---	--------	--------	---------	---------

Error:

Device Address	0x88	Error	CRC16_L	CRC16_H
----------------	------	-------	---------	---------

Function 16: MODBUS WRITE Register

Write multiple registers on the MODBUS address space starting with Start Address. Note, that the data will be written based on “MODBUS Register Map”.

Request:

Device Address	0x10	Start addr H	Start addr L	# Reg H	# Reg L	# Bytes	Data H	Data L	...	CRC16_L	CRC16_H
----------------	------	--------------	--------------	---------	---------	---------	--------	--------	-----	---------	---------

Response:



Device Address	0x10	Start addr H	Start addr L	# Reg H	#Reg L	CRC16_L	CRC16_H
----------------	------	--------------	--------------	---------	--------	---------	---------

Error:

Device Address	0x90	Error	CRC16_L	CRC16_H
----------------	------	-------	---------	---------

RTU character framing

Start bit	1	2	3	4	5	6	7	8	Even parity	Stop bit
-----------	---	---	---	---	---	---	---	---	-------------	----------

Note that this device only support baud rate 9600.

SB-WD Map register

word	name	R/W
0,1(Float IEEE754)	Range Of Direction(degree)	R
2,3(Float IEEE754)	Range of Speed(m/s)	R
4,5(Float IEEE754)	Sensor 1 Value	R
6,7(Float IEEE754)	Sensor 2 Value	R
8,9(Float IEEE754)	Sensor 3 Value	R
10(bit)	0-E1 1-E2 2-E3 3-E4 4-Sensor 1 Connection Error 5- Sensor 2 Connection Error 6- Sensor 3 Connection Error 7-Alarm 1 Status 8-Alarm 2 Status 9-Alarm 3 Status 10-Alarm 4 Status	R
11-Sensor 1 type and unit 12-Sensor 2 type and unit 13-Sensor 3 type and unit	0-type direction & unit degree 1-type speed & unit m/s 2-type speed & unit km/h 3-type speed & unit mph 4-type speed & unit knot 5-type speed & unit ft/s	R
14-19(char)	Model ID	R
20-25(char)	Serial Number	R
27-38(char)	Tag ID	R/W



SOFTWARE

SB-WD (01) is Portable device software; you can connect your device to computer with USB Cable (USB to Micro-USB) and configure your device or see measured value plots, save data...:

Min System Requirement:

- CPU: 2GHz.
- Memory: 2GB RAM.
- Hard Drive: 80 MB available in the hard disk.
- Windows 8 or superior.
- USB2 Port.

Software consists of three tabs:

- **DATA (Real Time):** Display measured value with a real time graph. Start, pause and erase data logging. Saving text file or a plot image from logged data. Display alarms status, errors, main and max values of measured value.
- **Configuration:** In this tab you can get device configuration or change configuration and set them to device, also you can reset device using reset factory.
- **Info:** In info tab you can change Tag ID of device. You can see device serial number registered by **Smart Biene**.

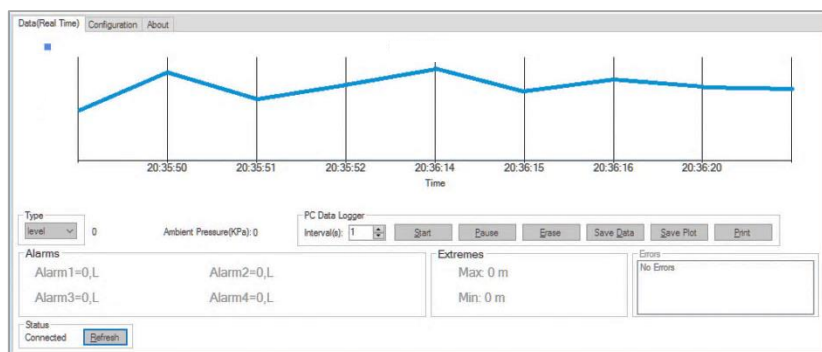


Figure 11: Device software- DATA (Real Time) Tab



Figure 12: Device software- info Tab



DIMENSIONAL DRAWING & INSTALLATION

The following illustrations show mounting examples and measurement setups.

(All dimensions in mm.)

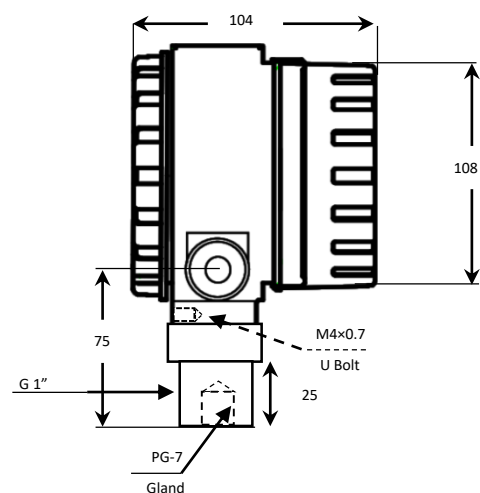
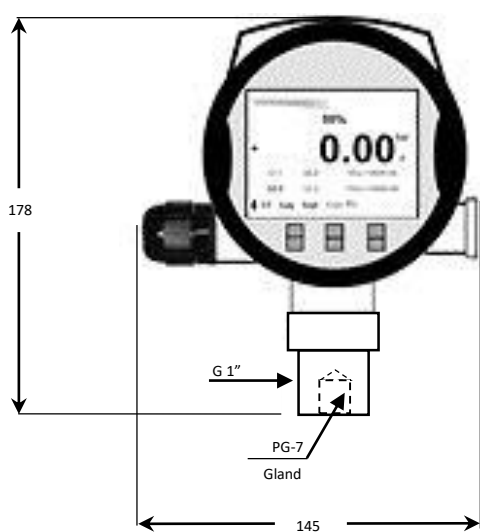


Figure 13: **SB-WD** Panel Dimensional Drawing s- all dimensions in mm.

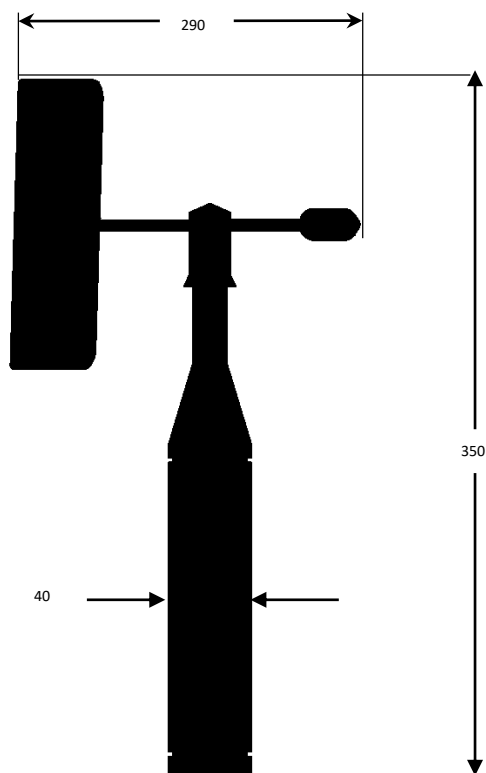


Figure 14: **SB-DS** Dimensional Drawing s- all dimensions in mm.

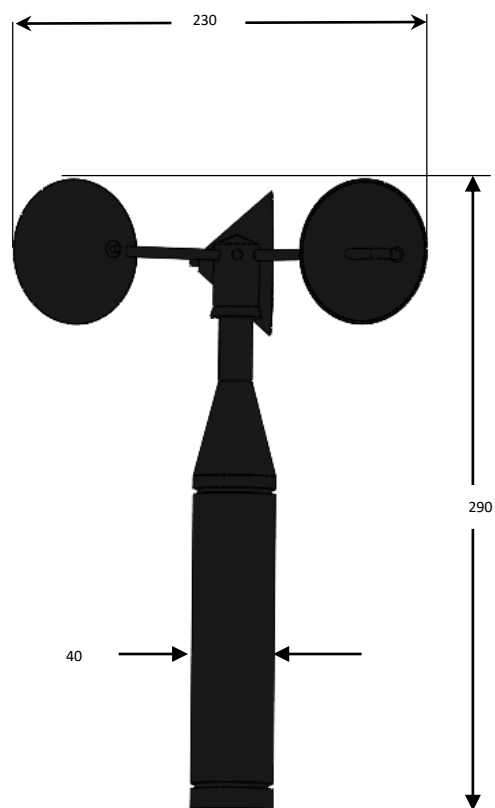


Figure 15: **SB-SS** Dimensional Drawing s- all dimensions in mm.



WARRANTY & DISCLAIMER

Smart Biene ENGINEERING, INC. warrants this unit to be free of defects in materials and workmanship for a period of 12 months from date of purchase. **Smart Biene's** WARRANTY adds an additional one (1) month grace period to the normal one (1) year product warranty to cover handling and shipping time. This ensures that **Smart Biene's** customers receive maximum coverage on each product. If the unit malfunctions, it must be returned to the factory for evaluation. **Smart Biene's** Customer Service Department will issue an Authorized Return (AR) number immediately upon phone or written request. Upon examination by **Smart Biene**, if the unit is found to be defective, it will be repaired or replaced at no charge. **Smart Biene's** WARRANTY does not apply to defects resulting from any action of the purchaser, including but not limited to mishandling, improper interfacing, operation outside of design limits, improper repair, or unauthorized modification. This WARRANTY is VOID if the unit shows evidence of having been tampered with or shows evidence of having been damaged as a result of excessive corrosion; or current, heat, moisture or vibration; improper specification; misapplication; misuse or other operating conditions outside of **Smart Biene's** control. Components, in which wear is not warranted, include but are not limited to contact points, fuses, and Relays. **Smart Biene** is pleased to offer suggestions on the use of its various products. However, **Smart Biene** neither assumes responsibility for any omissions or errors nor assumes liability for any damages that result from the use of its products in accordance with information provided by **Smart Biene**, either verbal or written. **Smart Biene** warrants only that the parts manufactured by the company will be as specified and free of defects.

Smart Biene MAKES NO OTHER WARRANTIES OR REPRESENTATIONS OF ANY KIND WHATSOEVER, EXPRESSED OR IMPLIED, EXCEPT THAT OF TITLE, AND ALL IMPLIED WARRANTIES INCLUDING ANY WARRANTY OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE HEREBY DISCLAIMED.

However, no responsibility is assumed by **Smart Biene** for using Device.

LIMITATION OF LIABILITY: The remedies of purchaser set forth herein are exclusive, and the total liability of **Smart Biene** with respect to this order, whether based on contract, warranty, negligence, indemnification, and strict liability or otherwise, shall not exceed the purchase price of the component upon which liability is based.

In no event shall **Smart Biene** be liable for consequential, incidental or special damages:

CONDITIONS: Equipment sold by **Smart Biene**. Is not intended to be used, nor shall it be used (1) as a "Basic Component" under 10 CFR 21 (NRC), used in or with any nuclear installation or activity; or (2) in medical applications or used on humans. Should any Product(s) be used in or with any nuclear installation or activity, medical application, used on humans, or misused in any way, **Smart Biene** assumes no responsibility as set forth in our basic WARRANTY/DISCLAIMER language, and, additionally, purchaser will indemnify **Smart Biene** and hold **Smart Biene** harmless from any liability or damage whatsoever arising out of the use of the Product(s) in such a manner General — Information in this document is believed to be accurate and reliable. However, **Smart Biene** does not give any representations or

Warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information.

Right to make changes — **Smart Biene** reserves the right to make Changes to information published in this document, including without

Limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — **Smart Biene** products are not designed, authorized or warranted to be suitable for use in medical, military, aircraft, space or life support equipment, nor in applications where failure or malfunction of an **Smart Biene** product can reasonably be expected.

WWW.SMARTBIENE.COM

Smart Measurement.

All specifications are subject to change without notice.

All sales subject to standard terms and conditions.

© Smart Biene

Email: info@smartbiene.com